

```
import time
```

This imports the time library so we can add delays in the program.

```
from adafruit_crickit import crickit
```

This imports the Crickit library so the CPX can talk to the Crickit board.

```
ss = crickit.seesaw
```

This creates a seesaw object which lets us read sensors and control outputs on Crickit.

```
photoresistor_1 = crickit.SIGNAL2
```

This connects the first photoresistor to signal pin 2.

```
photoresistor_2 = crickit.SIGNAL6
```

This connects the second photoresistor to signal pin 6.

```
moisture_sensor = crickit.SIGNAL8
```

This connects the moisture sensor to signal pin 8.

```
relay = crickit.SIGNAL7
```

This connects the relay to signal pin 7.

```
ss.pin_mode(photoresistor_1, ss.INPUT)
```

This sets the first photoresistor pin as an input.

```
ss.pin_mode(photoresistor_2, ss.INPUT)
```

This sets the second photoresistor pin as an input.

```
ss.pin_mode(moisture_sensor, ss.INPUT)
```

This sets the moisture sensor pin as an input.

```
ss.pin_mode(relay, ss.OUTPUT)
```

This sets the relay pin as an output so it can be switched on and off.

```
print("Plant monitoring system started")
```

This prints a message to show the program has started.

```
while True:
```

This creates a loop so the program runs forever.

```
moisture_value = ss.analog_read(moisture_sensor)
```

This reads how wet or dry the soil is.

```
light1 = ss.analog_read(photoresistor_1)
```

This reads the light level from the first photoresistor.

```
light2 = ss.analog_read(photoresistor_2)
```

This reads the light level from the second photoresistor.

```
print("Moisture:", moisture_value, "Light1:", light1, "Light2:", light2)
```

This displays all sensor values on the screen.

```
if moisture_value > 400:
```

This checks if the soil is dry.

```
ss.digital_write(relay, True)
```

This turns the relay on, which starts the water pump.

```
else:
```

This runs when the soil is not dry.

```
ss.digital_write(relay, False)
```

This turns the relay off, stopping the water pump.

```
time.sleep(1)
```

This waits one second before reading the sensors again.